

Two-minute presentation

Austrian-Kangaroos & Crane Control

Markus Bader

Vienna University of Technology
Automation and Control Institute (ACIN)
Work group: Vision4Robotics (V4R)

Austrian-Kangaroos

Framework

- Component based
- Monitoring
- Shared Memory
- Signals

Localization



Crane Control

Complex Dynamic System

Object Tracking

- Hook
- Obstacles

Video →



AK-Framework + ROS

