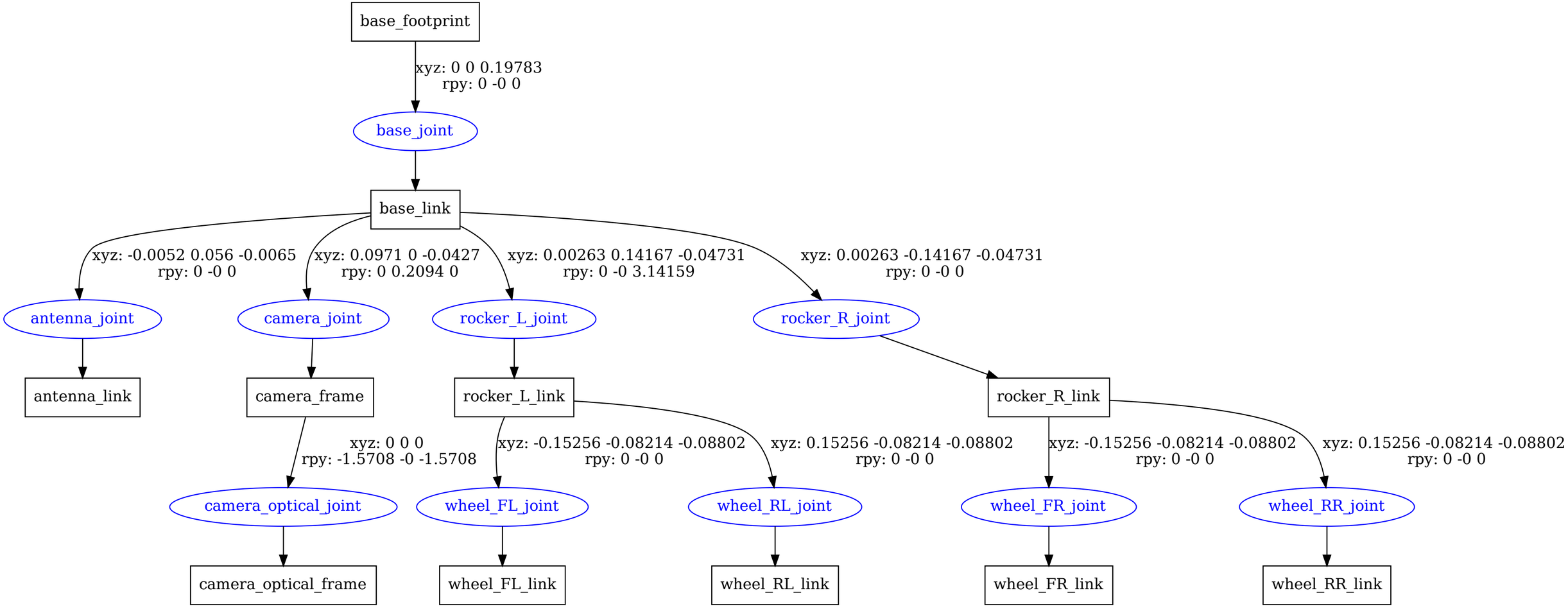
base_footprint
xyz: 0 0 0.19783
rpy: 0 -0 0
base_joint
base_link
xyz: -0.0052 0.056 -0.0065
rpy: 0 -0 0
xyz: 0.0971 0 -0.0427
rpy: 0 0.2094 0
xyz: 0.00263 0.14167 -0.04731
rpy: 0 -0 3.14159
xyz: 0.00263 -0.14167 -0.04731
rpy: 0 -0 0
antenna_joint
camera_joint
rocker_L_joint
rocker_R_joint
antenna_link
camera_frame
rocker_L_link
rocker_R_link
xyz: 0 0 0
rpy: -1.5708 -0 -1.5708
xyz: -0.15256 -0.08214 -0.08802
rpy: 0 -0 0
xyz: 0.15256 -0.08214 -0.08802
rpy: 0 -0 0
xyz: -0.15256 -0.08214 -0.08802
rpy: 0 -0 0
xyz: 0.15256 -0.08214 -0.08802
rpy: 0 -0 0
camera_optical_joint
wheel_FL_joint
wheel_RL_joint
wheel_FR_joint
wheel_RR_joint
camera_optical_frame
wheel_FL_link
wheel_RL_link
wheel_FR_link
wheel_RR_link